

## Combinatorial Optimization

### Exercise Sheet 12

#### Exercise 12.1:

Let  $f : 2^U \rightarrow \mathbb{R}$  be a submodular function. Let  $R$  be a random subset of  $U$ , where each element is chosen independently with probability  $\frac{1}{2}$ . Prove:

- (a)  $\mathbb{E}(f(R)) \geq \frac{1}{2}(f(\emptyset) + f(U))$ .
- (b) For each  $A \subseteq U$  we have  $\mathbb{E}(f(R)) \geq \frac{1}{4}(f(\emptyset) + f(A) + f(U \setminus A) + f(U))$ .
- (c) If  $f$  is nonnegative, then  $\mathbb{E}(f(R)) \geq \frac{1}{4} \max_{A \subseteq U} f(A)$ .

*Note:* Part (c) implies a randomized 4-factor approximation algorithm for (nonnegative) submodular function maximization. This problem cannot be solved optimally with a polynomial number of oracle calls. (4 Points)

#### Exercise 12.2:

Show that if we place the randomized step in the SIMPLE SUBMODULAR FUNCTION MAXIMIZATION ALGORITHM by setting  $A := A \cup \{i\}$  if  $\Delta_A \geq \Delta_B$  and  $B := B \setminus \{i\}$  otherwise yields a 3-approximation (deterministically, in linear time). (4 Points)

#### Exercise 12.3:

Consider the problem of finding an extreme point in the polytope defined in the proof of Buchbinder and Feldmann's deterministic polynomial-time 2-approximation algorithm for the problem of maximizing a nonnegative submodular function.

- (a) Replace one of the two nontrivial constraints by an objective function. Use this to show that there is an extreme point in which at most one variable has a fractional value.
- (b) Show how to solve the LP resulting from (a) in  $O(n \log n)$  time (note that  $|T_{i-1}| = O(n)$ ).

(4 Points)

*Continued on next page.*

**Exercise 12.4:**

For any METRIC TSP instance  $(K_n, c)$ , show that the integrality gap of the subtour-LP is at most  $\frac{3}{2}$ . The subtour-LP is given by

$$\begin{aligned} \min \quad & \sum_{e \in E} c_e x_e \\ \text{s.t.} \quad & x_e \in [0, 1] && (e \in E(K_n)), \\ & \sum_{e \in \delta(v)} x_e = 2 && (v \in V(K_n)), \\ & \sum_{e \in E(K_n[X])} x_e \leq |X| - 1 && (\emptyset \neq X \subset V(K_n)), \end{aligned}$$

and the integrality gap of a linear program is defined as the ratio of the cost of an optimum integral solution to the cost of an optimum (potentially fractional) solution. *Hint:* Recall Christofides' Algorithm. Show that for any vector  $x$  in the subtour polytope,  $\frac{1}{2}x$  is in the  $T$ -join polyhedron for every even set  $T$ . (4 Points)

**Deadline:** Tuesday, February 2, 2015, **before** the lecture.

**Information:** Submissions by groups of up to **three** students are allowed.