

An improved approximation guarantee for Prize-Collecting TSP

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Research Institute for Discrete Mathematics & Hausdorff Center for Mathematics
University of Bonn

Prize-Collecting TSP

Input:

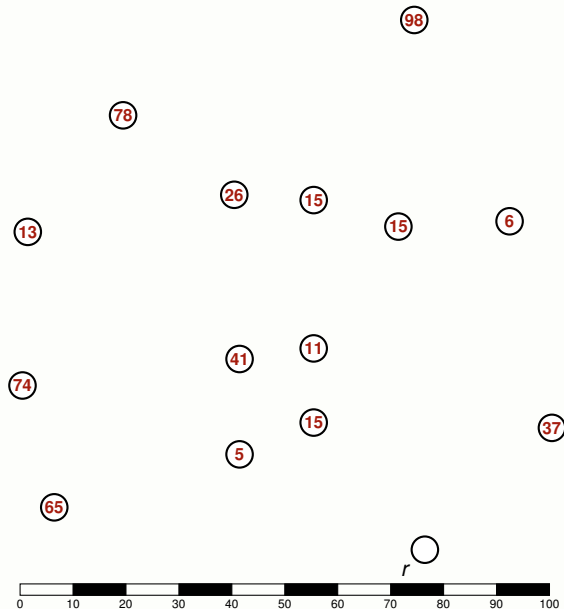
Complete $G = (V, E)$, root $r \in V$.

Metric $c: E \rightarrow \mathbb{R}_{\geq 0}$, penalties $\pi: V \setminus \{r\} \rightarrow \mathbb{R}$.

Task:

Find cycle $C = (V_C, E_C)$ in G covering r minimizing

$$\sum_{e \in E_C} c_e + \sum_{v \in V \setminus V_C} \pi_v .$$



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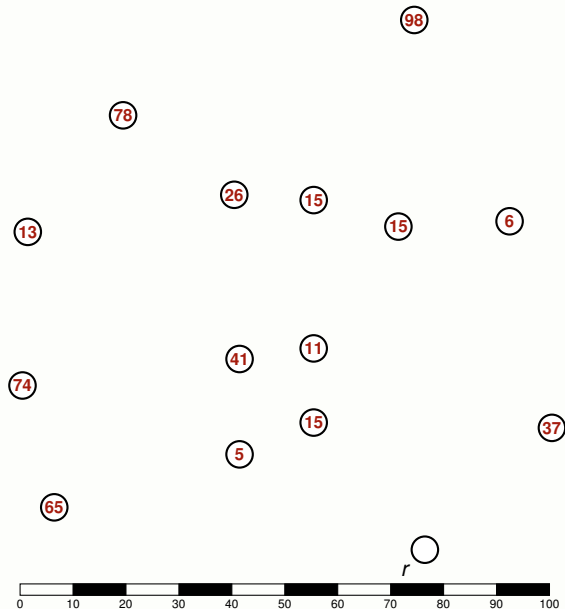
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connection cost

penalty cost



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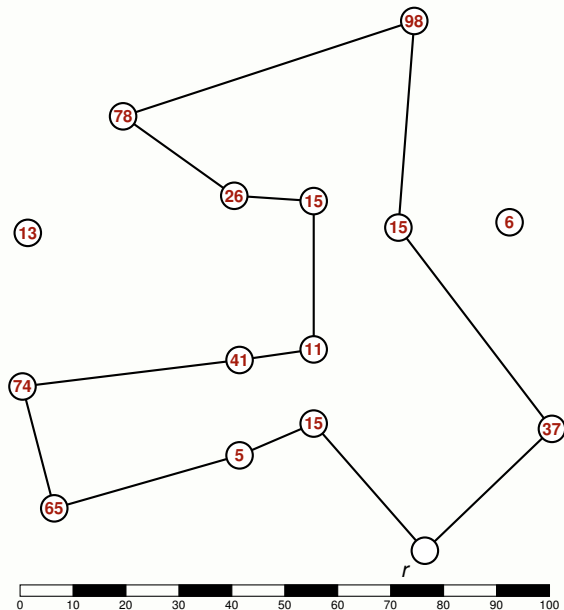
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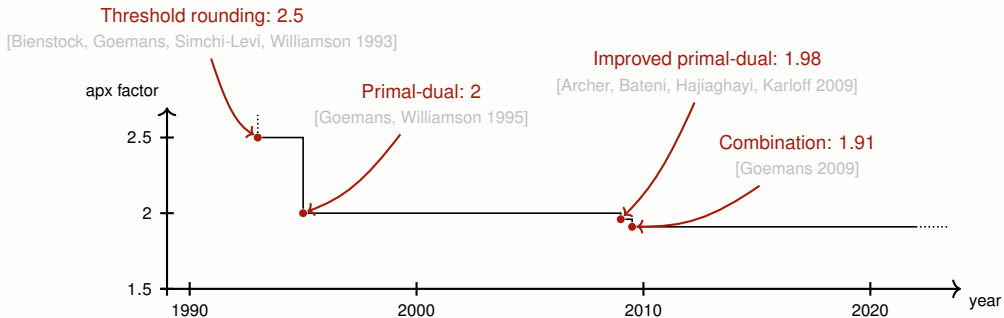
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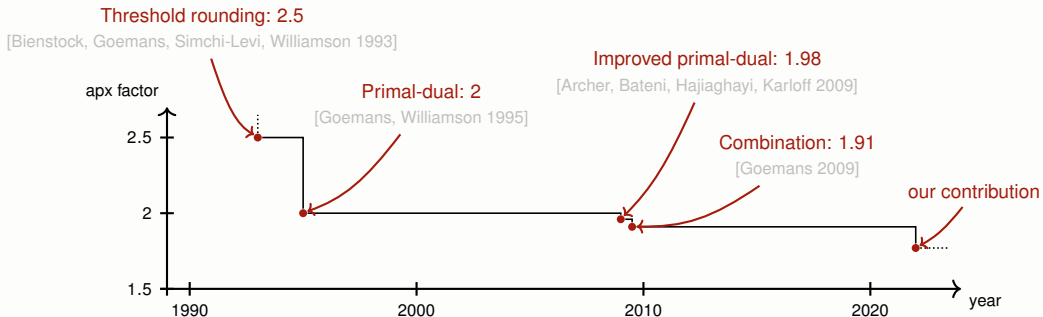
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Approximation algorithms



Approximation algorithms



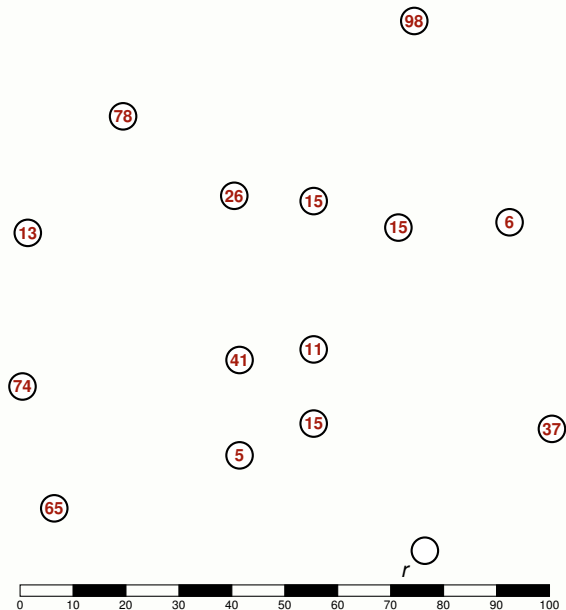
Theorem

There is an efficient 1.774-approximation algorithm for PCTSP.

[Blauth, Nägele 2022]

An LP formulation

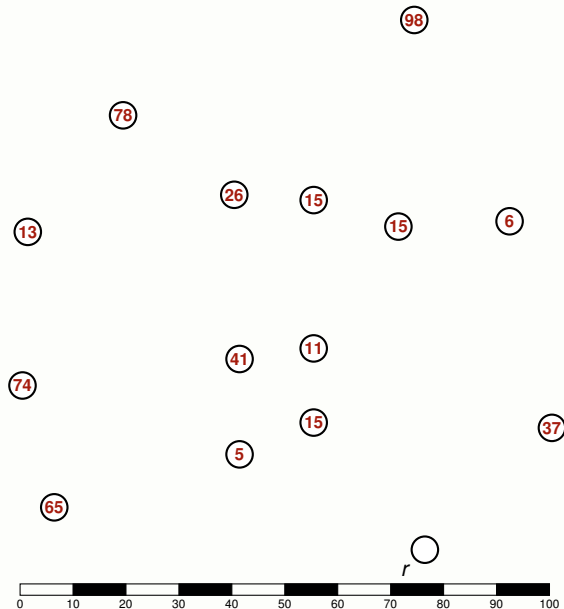
$$\begin{aligned}
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↑
vertex connectivity

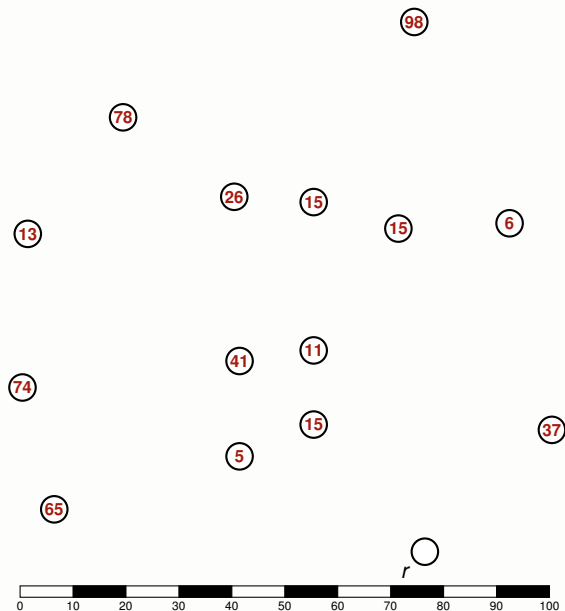


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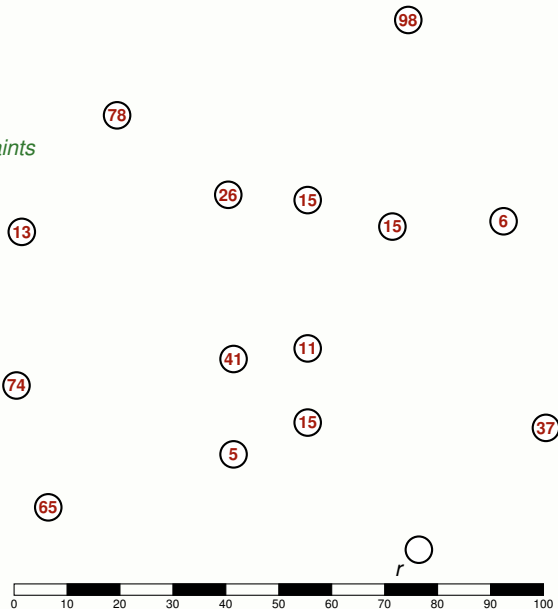
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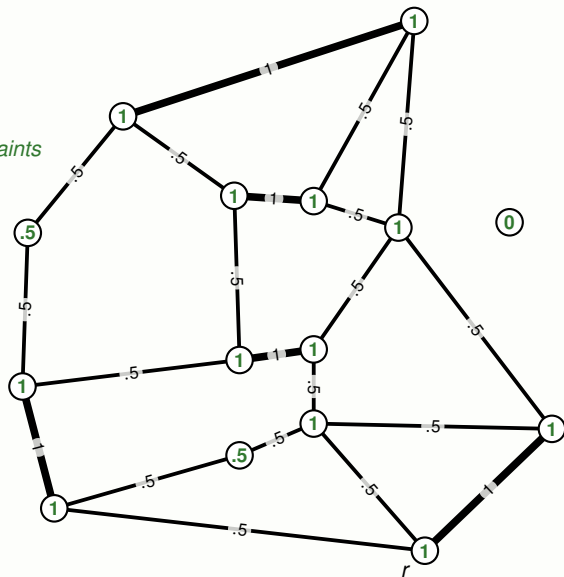
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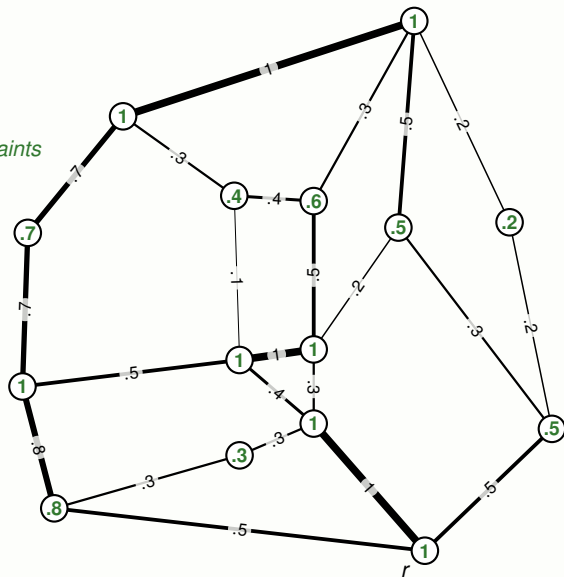
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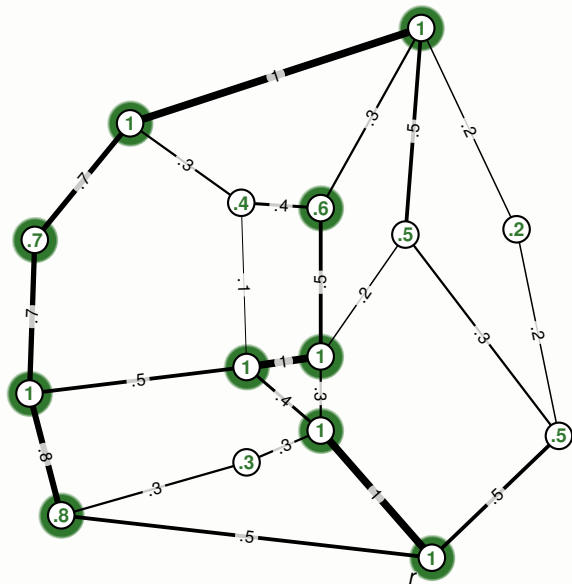
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Threshold rounding with threshold γ

Apply Christofides on $V_\gamma := \{v \in V : y_v \geq \gamma\}$.

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Example: $\gamma = 3/5$



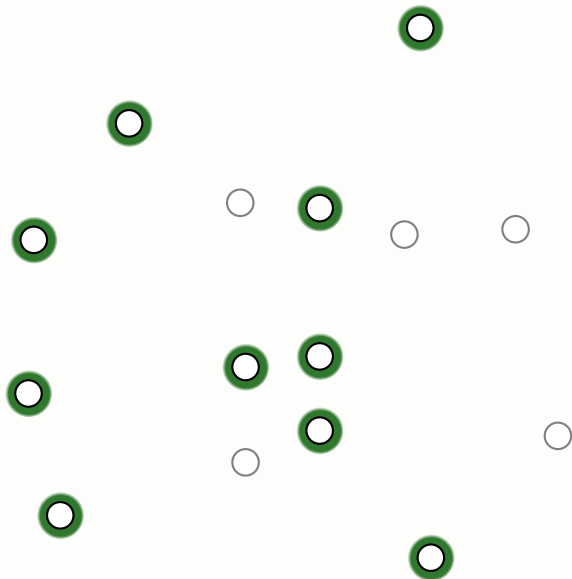
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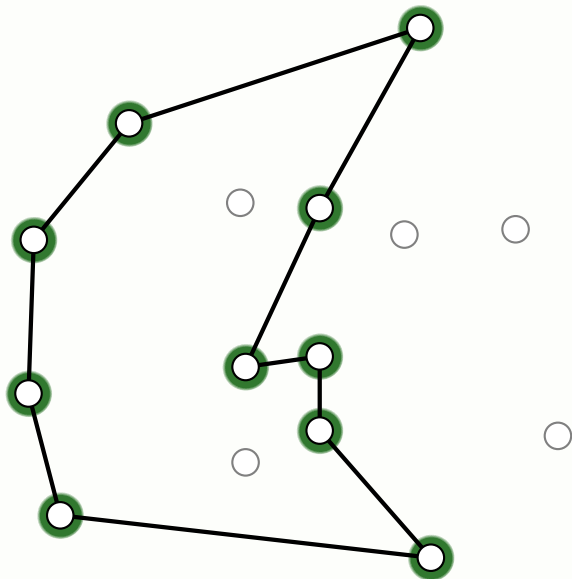
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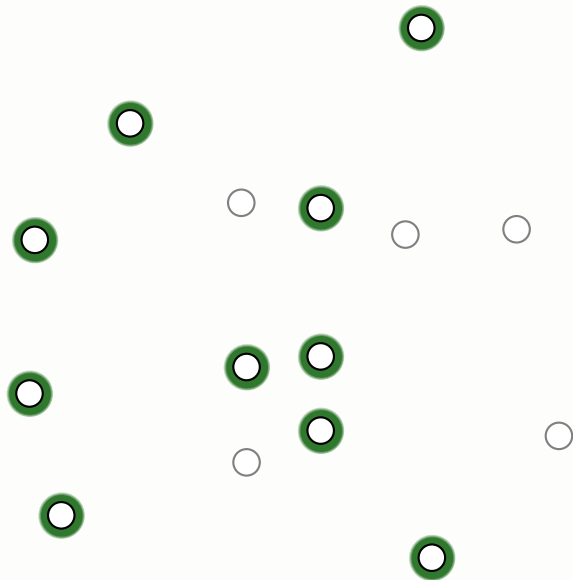
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Recalling Christofides' Algorithm

Christofides' Algorithm

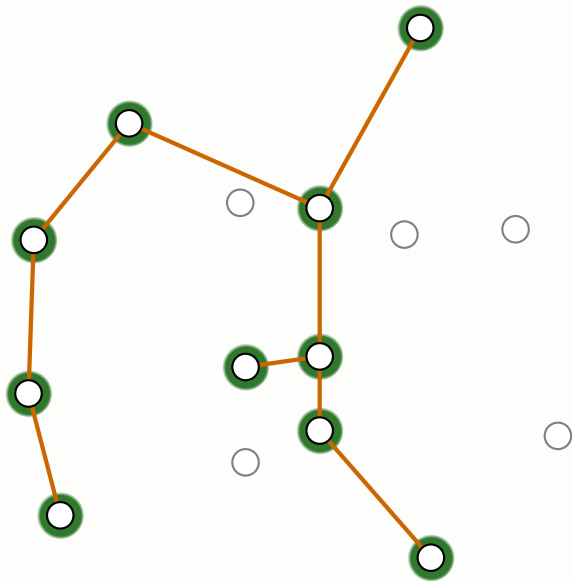
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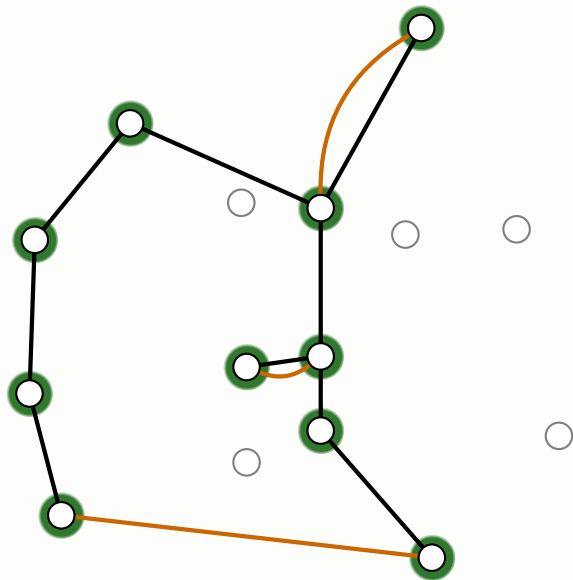
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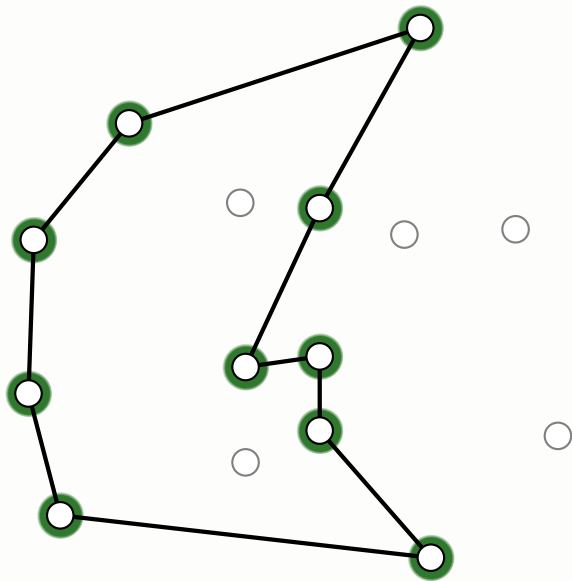
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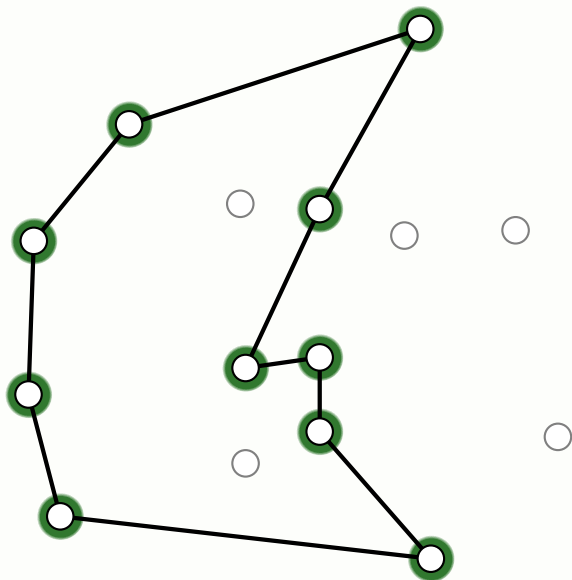
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Held-Karp relaxation:

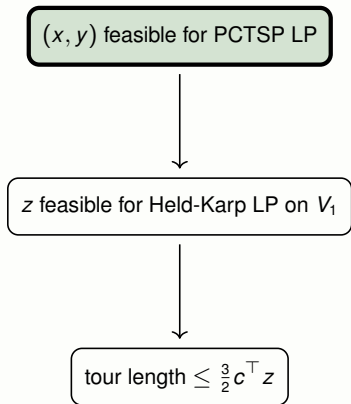
$$\begin{aligned} \min \quad & \sum_{e \in E} c_e x_e \\ x(\delta(v)) &= 2 \quad \forall v \in V \\ x(\delta(S)) &\geq 2 \quad \forall S \subsetneq V, S \neq \emptyset \\ x_e &\geq 0 \quad \forall e \in E \end{aligned}$$

Wolsey's analysis:

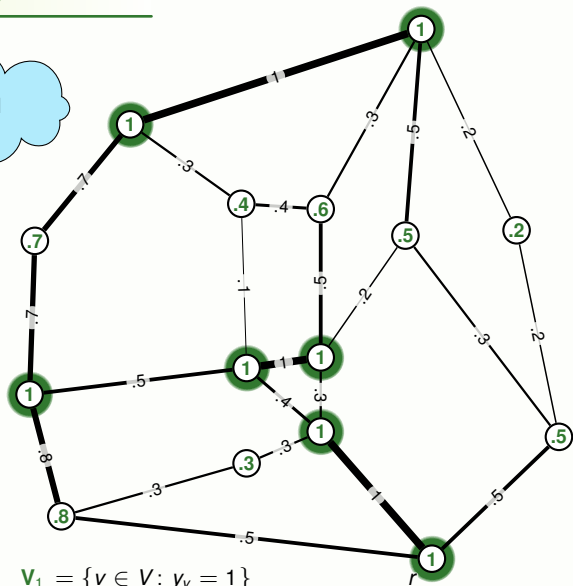
$$\begin{aligned} c(T) &\leq c^T x^* \quad \text{and} \quad c(J) \leq \frac{1}{2} c^T x^* \\ \implies & \text{LP-relative } 3/2\text{-approximation} \end{aligned}$$



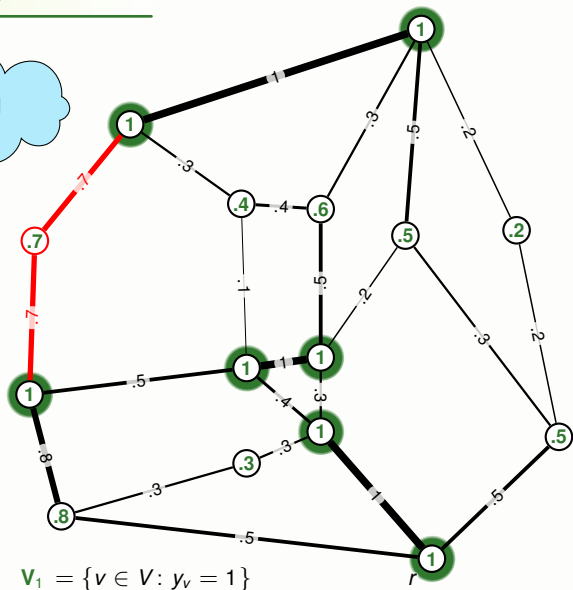
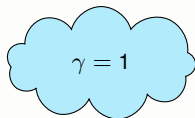
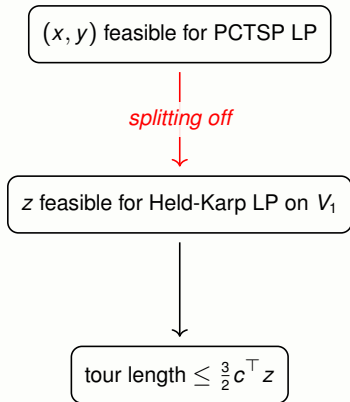
Analyzing threshold rounding: Linking the LPs



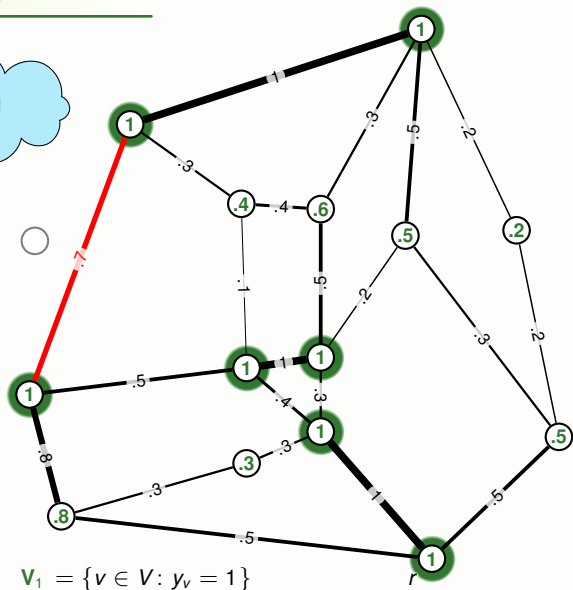
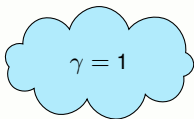
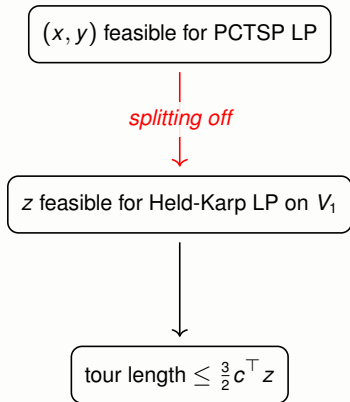
$\gamma = 1$



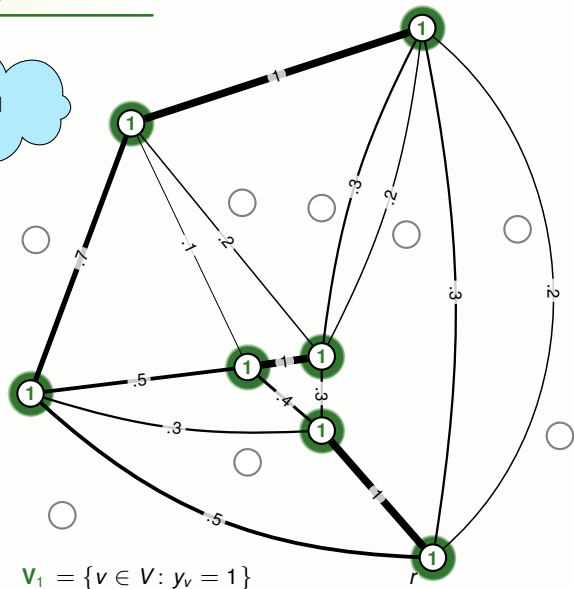
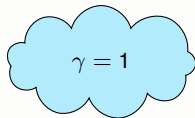
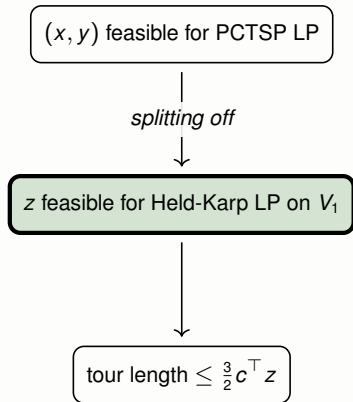
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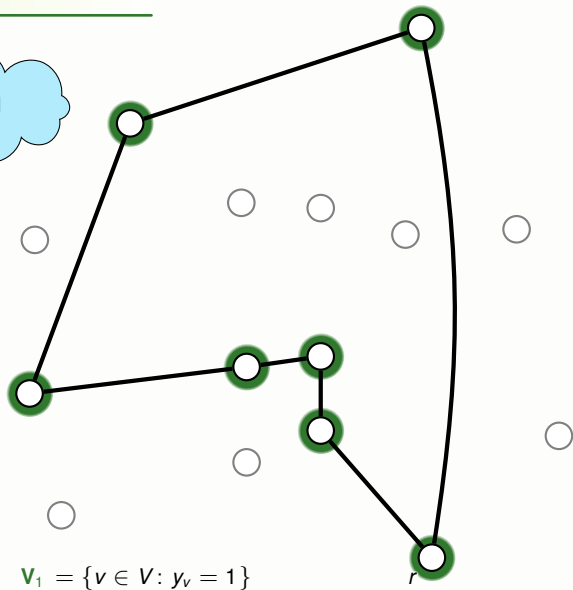
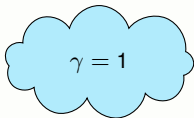
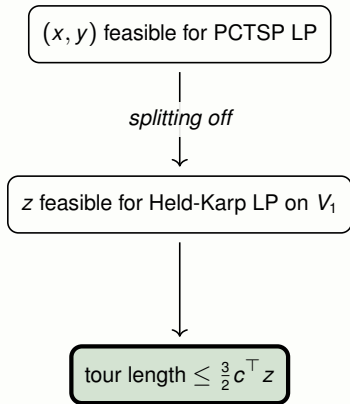
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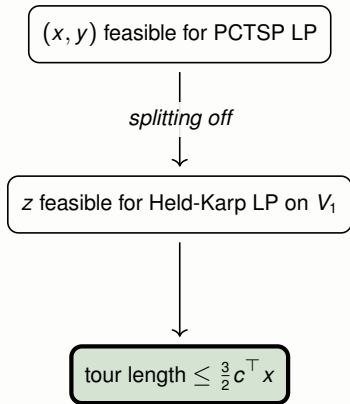
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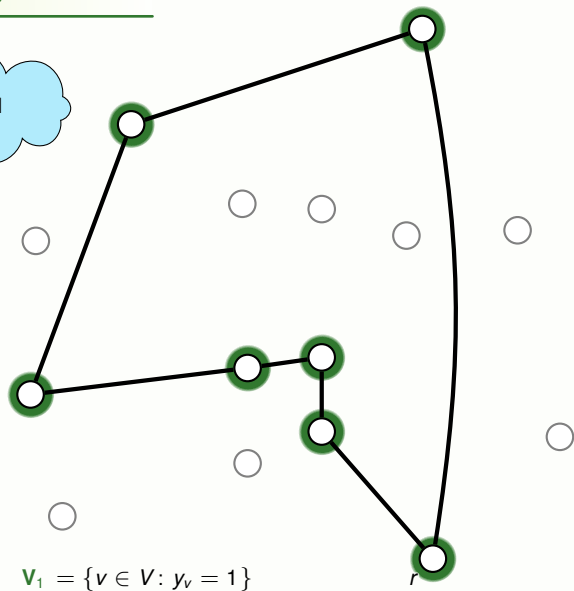
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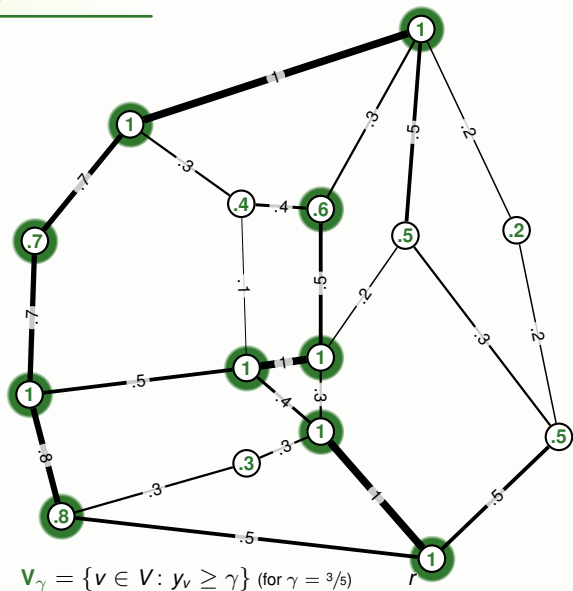
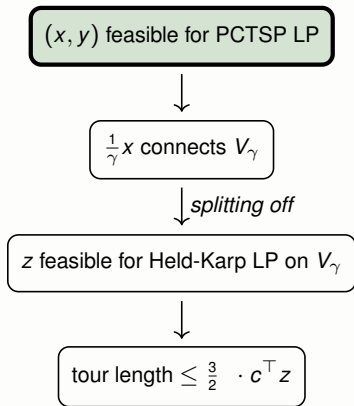
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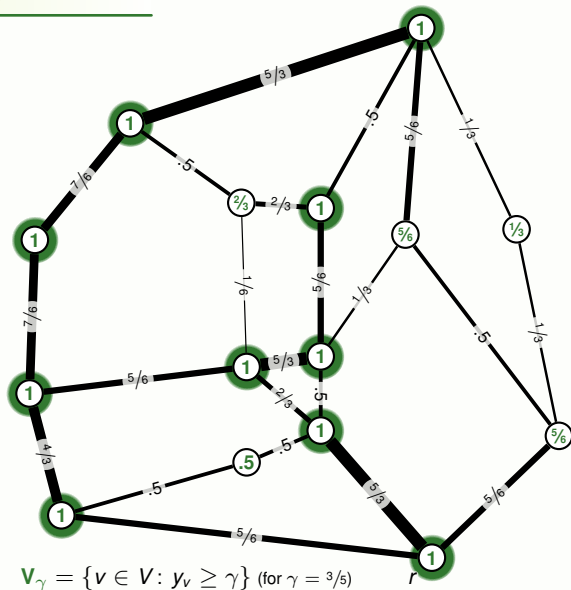
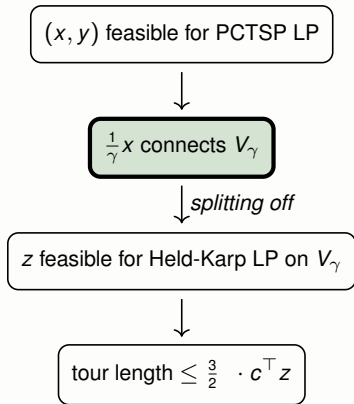
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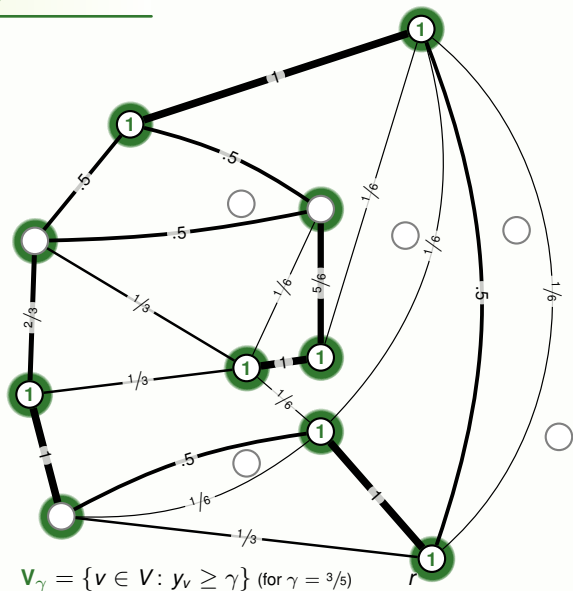
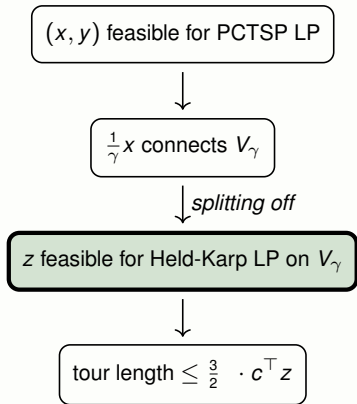
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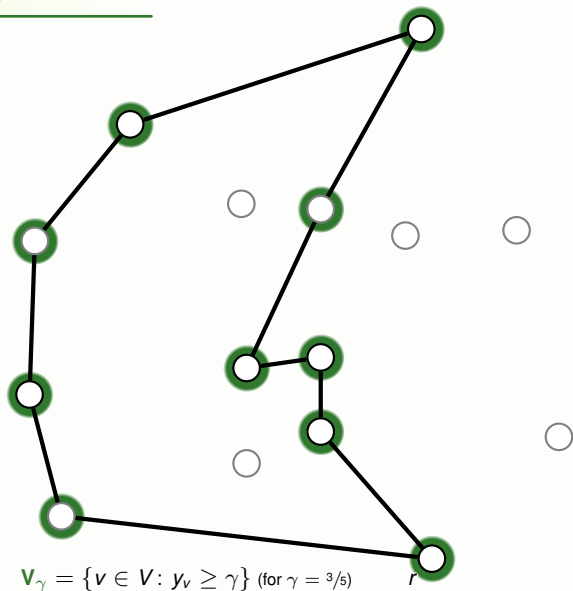
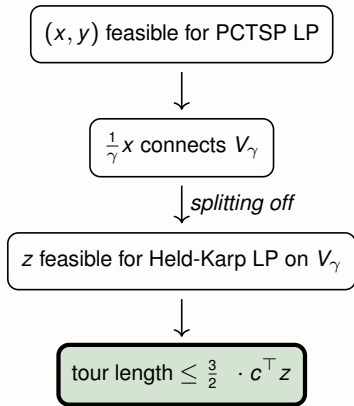
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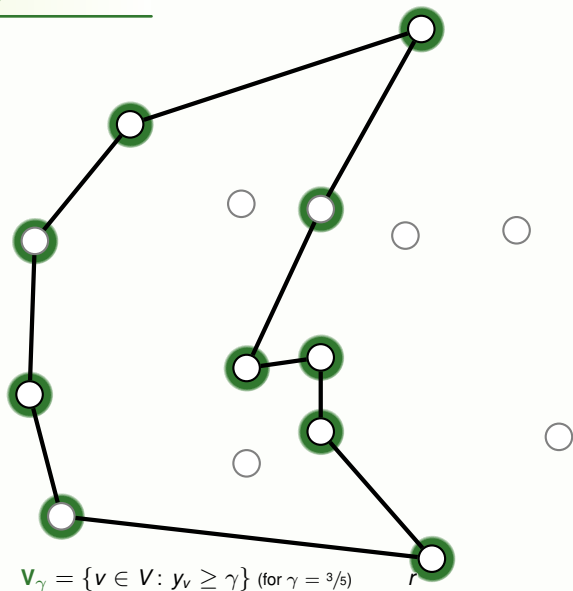
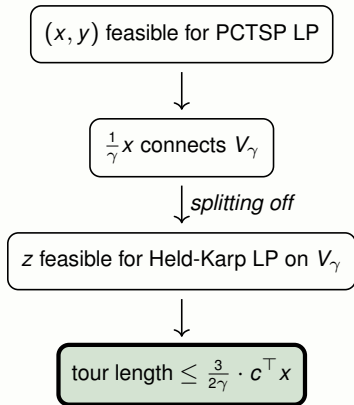
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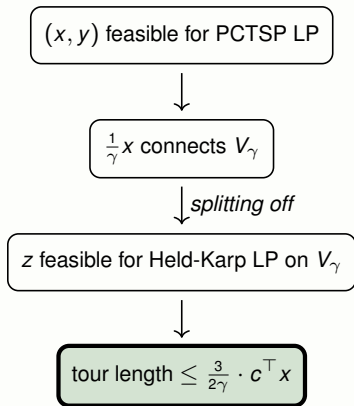
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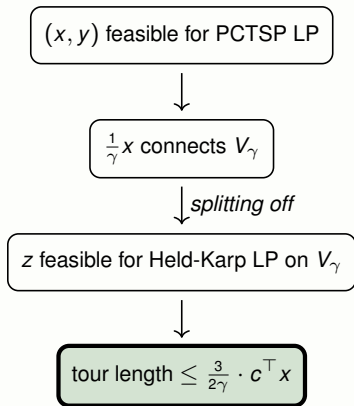
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Incurred penalties:

$$\begin{aligned} \sum_{v \notin V_\gamma} \pi_v &= \sum_{v \in V: y_v < \gamma} \pi_v \\ &\leq \sum_{v \in V: y_v < \gamma} \frac{1 - y_v}{1 - \gamma} \pi_v \end{aligned}$$

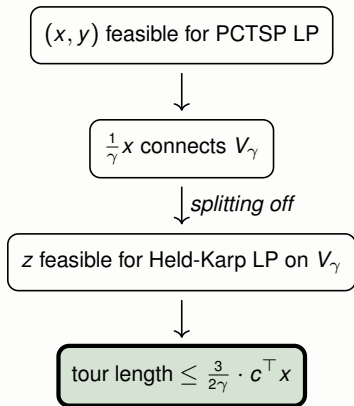
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Analyzing threshold rounding: Linking the LPs



Theorem

$5/2$ -approximation for $\gamma = 3/5$.

[Bienstock, Goemans, Simchi-Levi,
Williamson, 1993]

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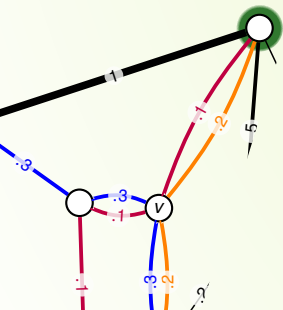
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Improving the approximation guarantee

— beyond thresholding —



A major weakness of thresholding

- ▶ Transformation from LP solution x to Held-Karp solution z :



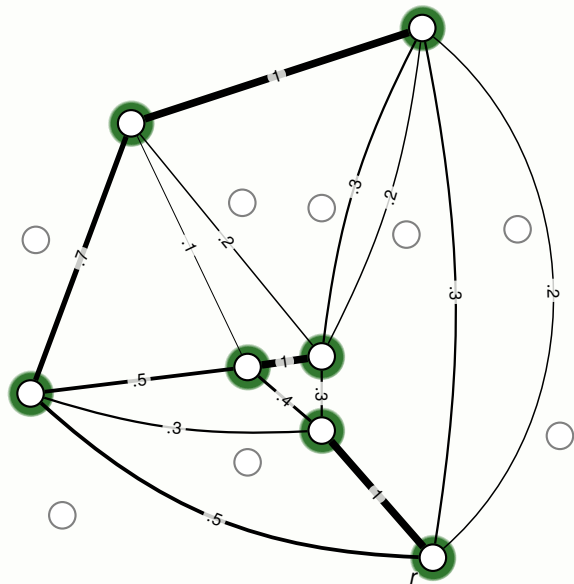
Idea: Unpack splitting off operations

- ▶ Can we stay within the budget $\frac{3}{2} c^T x$?
- ▶ Can we improve the bound on the penalty?

Opening the blackbox

Christofides' Algorithm

1. Take a shortest spanning tree T .
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3. Shortcut.



$z \in P_{HK}$ obtained from PCTSP solution x

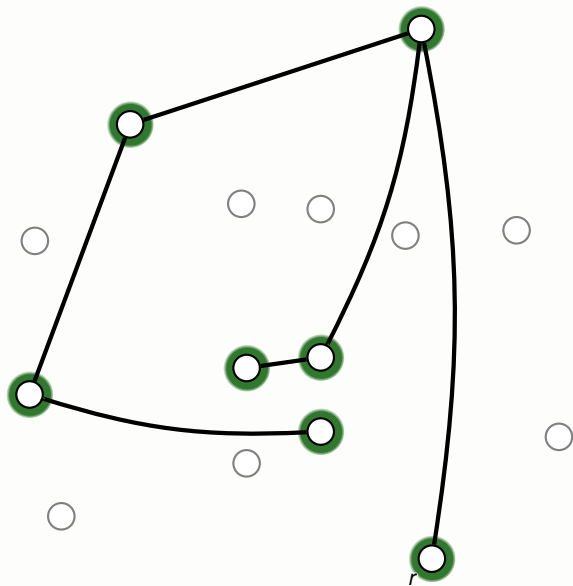
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1.' Sample T with marginals $\approx z$, undo splitting off for sampled edges.

$$\implies \mathbb{E}[c(T)] \leq c^T x$$

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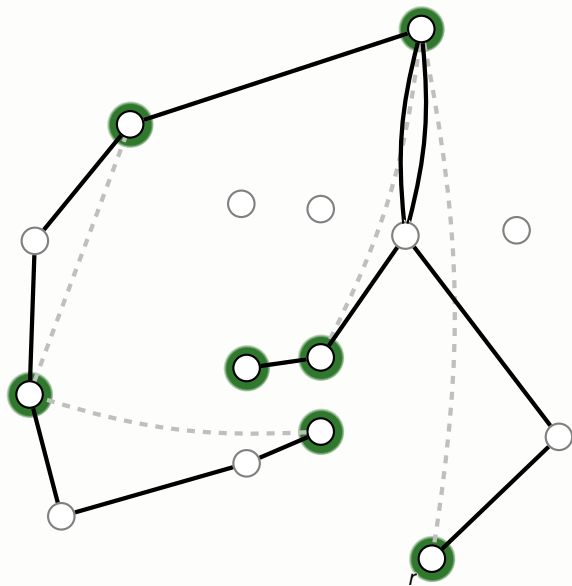
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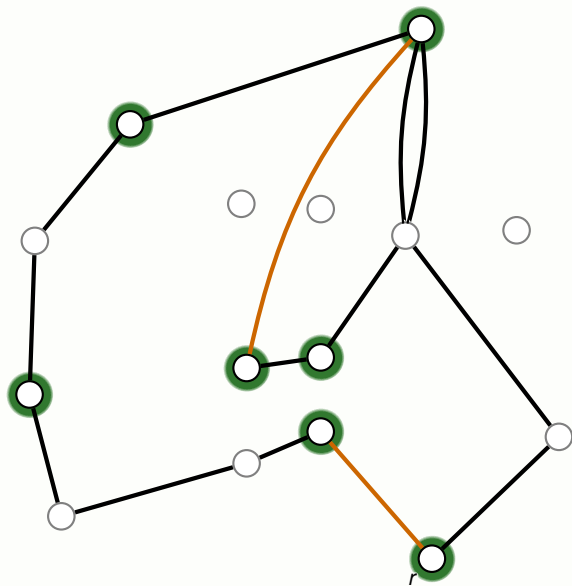
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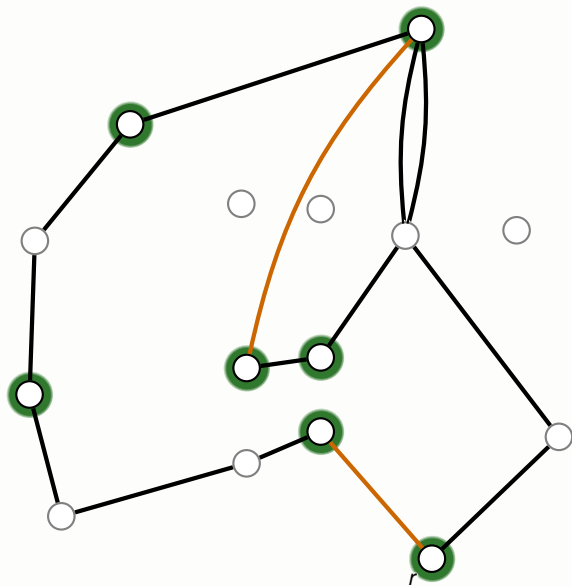
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We have $\text{odd}(T) \subseteq V_\gamma$!

$$\implies \mathbb{E}[c(J)] \leq \frac{1}{2} c^T z \leq \frac{1}{2} c^T x$$



Opening the blackbox

- 1.' Sample T with marginals $\approx z$, undo splitting off for sampled edges.

$$\implies \mathbb{E}[c(T)] \leq c^\top x$$

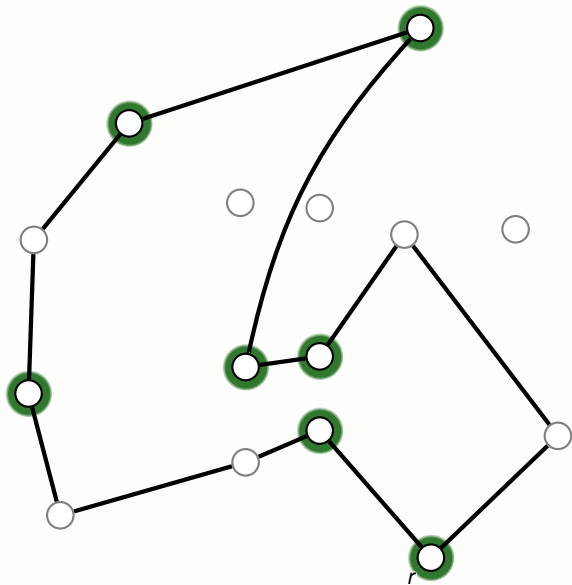
Christofides' Algorithm

1. Take a shortest spanning tree T .
2. Add a shortest odd(T)-join J .
3. Shortcut.

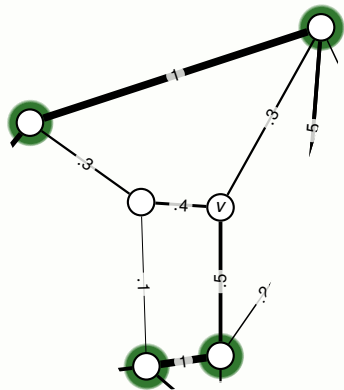
We have $\text{odd}(T) \subseteq V_\gamma$!

$$\implies \mathbb{E}[c(J)] \leq \frac{1}{2} c^\top z \leq \frac{1}{2} c^\top x$$

\implies Extra coverage at expected cost $\frac{3}{2} c^\top x$.



Analyzing penalties

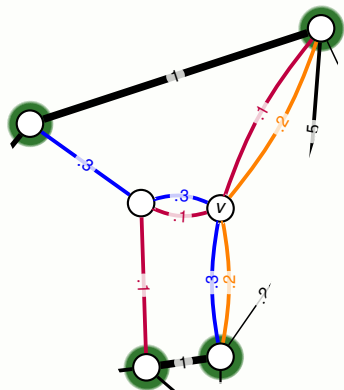


Excerpt of the PCTSP LP solution x .

For $v \notin V_\gamma$, we want to bound

$$\mathbb{P}[v \text{ is not covered by the extended tree}]$$

Analyzing penalties



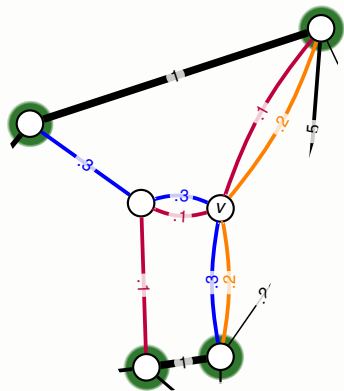
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Analyzing penalties



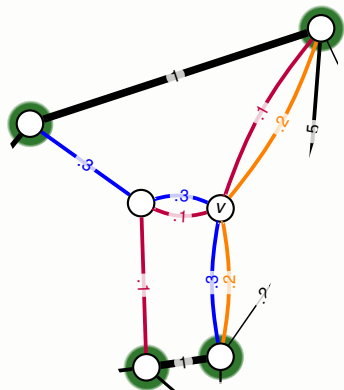
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negative correlation

Analyzing penalties



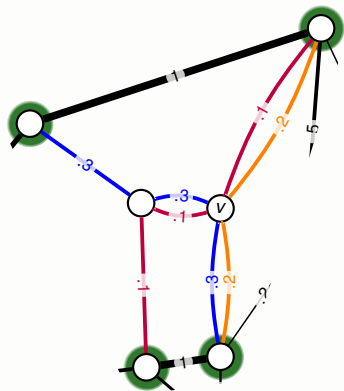
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negative correlation

Analyzing penalties

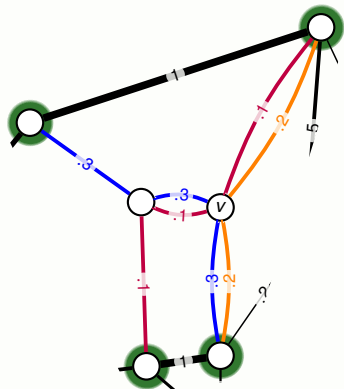


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Analyzing penalties



Excerpt of the PCTSP LP solution x .

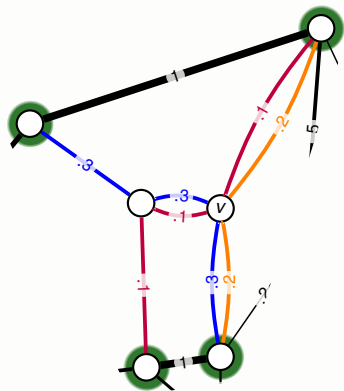
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 &\leq \exp\left(-\sum_{w \in W_v} z_w\right) = \exp(-y_v) .
 \end{aligned}$$

negative correlation

if walks pass through v once

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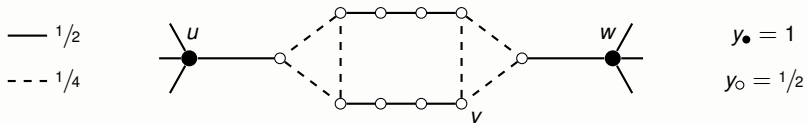
if walks pass through v once

$$\Rightarrow \text{total expected penalty } \sum_{v \in V: y_v < \gamma} \exp(-y_v) \cdot \pi_v$$

We are not done yet!

(Wrong) assumption

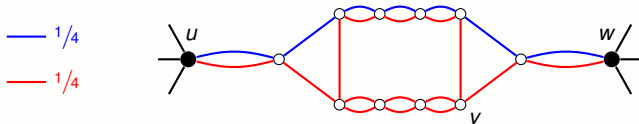
Total weight of walks at v after undoing splitting = y_v .



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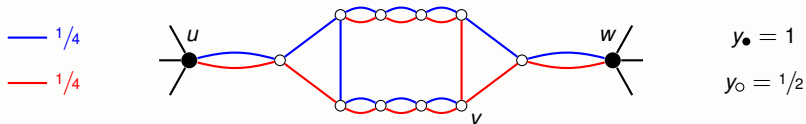
$$y_{\bullet} = 1$$

$$y_{\circ} = 1/2$$

We are not done yet!

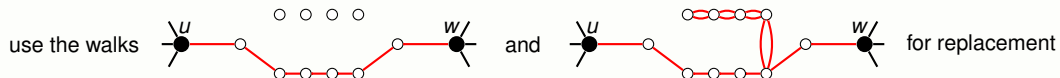
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Total weight of walks at v after undoing splitting = y_v .



Solution

Construct **trees** when undoing splitting s.t.
 $y_v = \text{total tree weight at } v$.



Theorem

Let (x^*, y^*) be a PCTSP LP solution. For threshold $\gamma \in (0, 1]$, we get in poly time a cycle $C = (V_C, E_C)$ with

$$c(E_C) + \pi(V \setminus V_C) \leq \frac{3}{2\gamma} \cdot c^T x^* + \sum_{v \in V: y_v^* < \gamma} \pi_v \cdot \exp\left(-\frac{3y_v^*}{4\gamma}\right).$$

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► To compare to the LP value:

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- Better guarantee through randomized choice of γ .

A randomized threshold choice

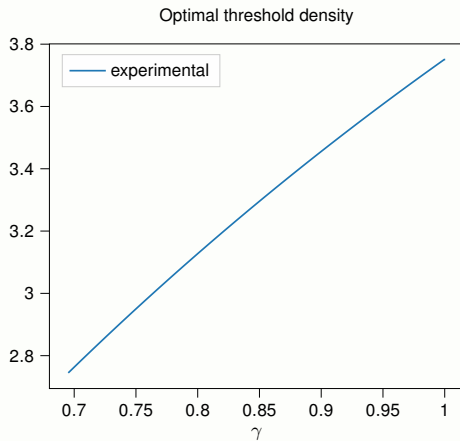
Discretization: $\gamma_i = \frac{i}{N}$ for $i \in [N]$ and $y_j = \frac{j}{N}$ for $j \in [N]$.

$$\min \left\{ \alpha : \begin{array}{l} \sum_{i \in \{1, \dots, N\}} \frac{3}{2\gamma_i} z_i \leq \alpha \\ \sum_{i \in \{1, \dots, N\}: \gamma_i > y_j} \exp\left(-\frac{3y_j}{4\gamma_i}\right) z_i \leq (1 - y_j) \cdot \alpha \quad \forall j \in [N] \\ \sum_{i \in \{1, \dots, N\}} z_i = 1 \\ z_i \geq 0 \quad \forall i \in [N] \end{array} \right\}$$

cycle cost
penalty costs at y_j

probability for choosing threshold γ_i

A randomized threshold choice

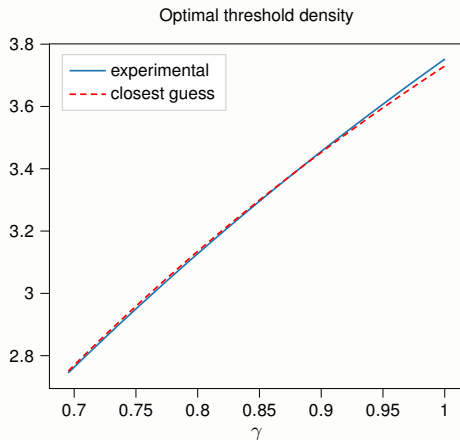


LP solution:

optimal value $\alpha \approx 1.773$

non-zero on interval $[b, 1]$ for $b \approx 0.6952$

A randomized threshold choice



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Closest guess:

Proportional to $\exp(-b/\gamma)$ on $[b, 1]$.

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- Such randomized choice of γ gives an approximation guarantee

$$\alpha = \frac{\max\left\{\int_b^1 \frac{3}{2\gamma} \exp(-b/\gamma) d\gamma, \max_{y \in [0,1]} \frac{1}{1-y} \int_{\max\{b,y\}}^1 \exp\left(-\frac{3y}{4\gamma}\right) \exp(-b/\gamma) d\gamma\right\}}{\int_b^1 \exp(-b/\gamma) d\gamma}.$$

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For $b = 0.6945$, we can show $\alpha < 1.774$.

- LP technique gives computational lower bound > 1.773 .

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Paper available at
arxiv.org/abs/2212.03776!